# DULL Δ Aerospace Engineer

Abu Dhabi, UAE

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**Research Engineer** 

**CENTER FOR ARTIFICIAL INTELLIGENCE AND ROBOTICS** 

- Working on Aerial Omnidirectional manipulators that have independent translational and rotational DOFs
- Working robotic artificial limbs and using AI to control them with brain signals
- Providing support to the ongoing projects by designing and manufacturing the needed setups.

#### **Visiting Researcher**

KU CENTER FOR AUTONOMOUS ROBOTIC SYSTEMS

• Worked on the Houbara project which aimed to create a bird robot to interactively monitor the Houbara birds.

#### **Space Systems Engineer**

YAHSAT SPACE LAB-KHALIFA UNIVERSITY

- 01/2021 07/2022
- Co-operated with a 7 MSc students to perform the mission concept revirew of a 6U CubeSat with On-board micro propulsion.
- Sized the ADCS for the 6U CubeSAT and analyzed the expected disturbances.
- Studied the ADCS performance along with the propulsion system to perform orbital maneuvers.
- Performed the comparative analysis required to select the ADCS from the components off the shelf.

#### **Enterpreneur and Founder**

CUBETUMBLE

- A newly found startup that offers solutions for CubeSats' ADCS testing.
- Mentored by Khalifa Innovation Center (KIC).

### **Aircraft Designer - Internship**

ARAB ORGANIZATION FOR INDUSTRIALIZATION

Cairo, Egypt 06/2019 - 09/2019

Cairo, Egypt

Spring 2015

Abu Dhabi, UAE

06/2022 - 12/2022

- Designed the planform and stability response for a fixed-wing UAV.
- Carried on the drag analysis and calculated the needed thrust for the mission.
- Designed and manufactured a 500g fiber glass wing and a 200g fiber glass tail

### **Junior Teaching assistant**

UNIVERSITY OF SCIENCE AND TECHNOLOGY - ZEWAIL CITY

Course: Modelling and Linear Control



## **ABOUT ME**

Aerospace Engineer, Robotics, Aircraft designer, ADCS proficient, Control Theory

# SKILLS

C-C++

Arduino

LabVIEW

Abaqus

SolidWorks

STK

Ansys

MATLAB

Simulink

Web Development

### LANGUAGES

Arabic • Mother tongue **English** • Fluent French • Conversational

# HOBBIES

Writing, Cycling, Chess

Abu Dhabi, UAE



10/2022 - 12/2022

# Abu Dhabi, UAE

Abu Dhabi, UAE 03/2023 - Current



#### **Master of Science**

KHALIFA UNIVERSITY OF SCIENCE AND TECHNOLOGY

- Major: Mechanical Engineering
- Concentration: Space Systems and Technology
- GPA: 3.89

#### **Bachelor of Science**

UNIVERSITY OF SCIENCE AND TECHNOLOGY - ZEWAIL CITY

- Major: Aerospace Engineering
- GPÁ: 3.67
- Honors: Cum Laude

#### **High School**

STEM EGYPT FOR BOYS

• GPA: 4

# Cairo, Egypt

Abu Dhabi, UAE

08/2020 - 07/2022

09/2015 - 07/2020

Cairo, Egypt 09/2012 - 07/2015

# PROJECTS

#### "Designing and manfacturing an optimized Aerial Omnidirectional manipulator Abu Dhabi,

IIAF

CAIR PROJECT

03/2023 - Current

- Solving for an optimal design for hexarotor omnidirectional drone with multiple constraints.
- Designing and manufacturing the optimized design and the gripper.
- Building a controller for the six independent DOFs and the gripper.

#### "Development of an Experimental Setup for CubeSat Attitude **Determination and Control** Abu Dhabi, UAE

MASTER'S THESIS

01/2021 - 07/2022

- Utilized air bearings to manufacture an ADCS testbed for any 1U CubeSat.
- Designed and manufactured the utilized air bearing.
- Manufactured and programmed a system to balance the center of gravity for the testbed.
- Added a system of reaction wheels to actuate the setup.

#### Guidance and Control of a Subsonic Sounding Rocket and Suborbital Cylindrical Satellite Design and Deployment Cairo.

Egypt

ZEWAIL CITY - EGYPTIAN MILITARY TECHNICAL COLLEGE - EGYPTIAN SPACE AGENCY 09/2019 - 07/2020

- Applied Proportional Navigation to control a canard configuration sounding rocket to reach an altitude of 20 km as the first phase of the project
- Optimized the rocket trajectory to achieve the required end conditions for orbit insertion.
- Tested the performance of the control unit using a predefined trajectory and hardware-in-the-loop setup.

#### **Designing and Manufacturing a Heavy-Lift Fixed Wing Unmanned Air Vehicle** California, USA 07/2018 - 04/2019

SAE Aero Design West Competition

- Co-operated with a team of 12 to design a UAV with a wing span of 3m.
- Responsible for the conceptual and preliminary design of the aircraft to carry around 16 kg of payload with the maximum of 1000 watts.
- Carried on the planform & stability design and the drag analysis.

### **Ground tracker Software**

**ORBITAL MECHANICS COURSE (UNDERGRADUATE)** 

- Cairo, Egypt Spring 2018
- Developing a GUI to track an object in any orbit using Gibbs method and Gauss method.
- MATLAB was used to program the code and the GUI

# EXTRACURRICULAR ACTIVITIES

Spring 2015 <b>Co-founder</b> , Zewail University Chess Club	Cairo, Egypt
Fall 2016 <b>Head of Engineering committee,</b> IEEE Zewail University	Cairo, Egypt
Summer <b>Speaker</b> , Zewail City Science Festival	Cairo, Egypt
2017- 2018 Writer, Journalism committee in Zewail City	Cairo, Egypt
Spring 2019 <b>Co-founder,</b> Flight Team - Zewail City	Cairo, Egypt
2022 Member, Chess Club in Khalifa University	Abu Dhabi, UAE